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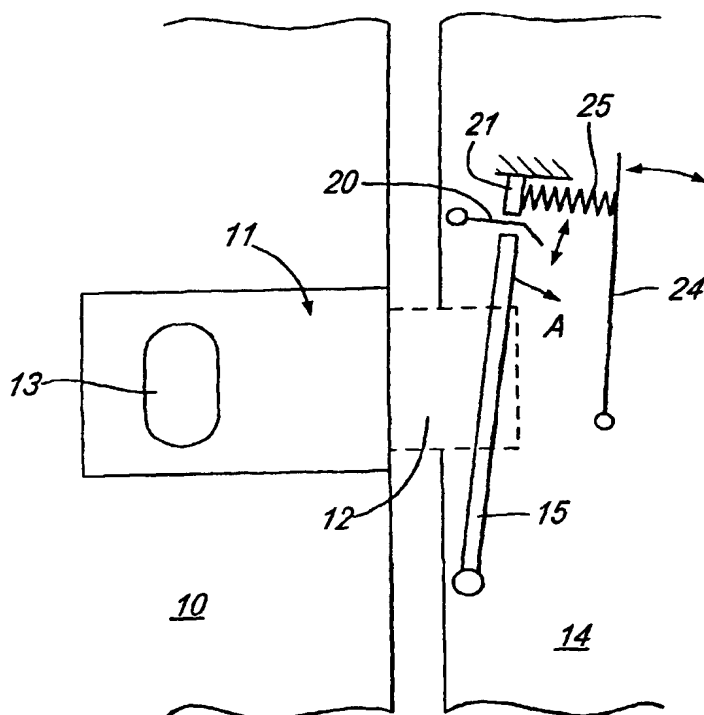
(71) **Applicant (*for all designated States except US*):** PBT (IP) LIMITED [GB/GB]; 1 Astra Centre, Edinburgh Way, Harlow, Essex CM20 2BN (GB).

(72) **Inventor; and**

(75) **Inventor/Applicant (*for US only*):** POWELL, Simon [GB/GB]; 51 Old North Road, Royston, Herts SG8 5EP (GB).

[Continued on next page]

- (54) Title:** ELECTRICALLY CONTROLLED DOOR LOCK



- (57) Abstract:** An electrically controlled door lock (11) provided with a blocking member (21) and a detent (20), the blocking member being in contact with an electrically controlled actuator (24) such as a piezo-electric member which is used to control movement of the blocking member which in turn causes either the release of a locking member (12) from a door to allow the door to be opened or the engagement of the locking member to prevent the door from being opened.



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ELECTRICALLY CONTROLLED DOOR LOCK

The present invention relates to door locks and more particularly to a door lock which is electrically controlled.

5 It is known to provide door locks which are a combination of a conventional door lock which can be activated by a key but which can also be released by means of an electrical control signal so that the door can be pushed open without the use of a key. These are common in apartment blocks.

10 Customarily, the electrical control signal is used to move a member out of position to such an extent that the locking member attached to the door no longer prevents the door being pushed open.

Despite the fact that such locks have been available for a considerable number of years, there still exists the need to provide a reliable electrically actuated arrangement at low cost and particularly one which can be installed in
15 either a normally closed or normally open condition.

The present invention provides an electrically activated door lock in which a piezo electric member is used to control movement of a blocking member which in turn controls the latching of the door.

20 Preferably, the blocking member and the retaining member are shaped so as to permit movement of the blocking member to either release the locking member to allow a door to be opened or engage the member so as to prevent the door being opened.

In order that the present invention be more readily understood, an embodiments thereof will now be described by way of example with reference to
25 the accompanying drawings in which:-

Fig 1 shows a diagrammatic representation of an electrically activated latching mechanism according to a first embodiment of the present invention;

Fig 2 shows diagrammatically a reversing mechanism capable of altering the operation of the mechanism shown in Fig 1 from a normally open condition to a normally closed condition;

Fig 3 shows a section of the electrically actuated latching mechanism according to a second embodiment of the present invention;

Fig 4 shows the mechanism shown in Fig 3 initially set in a reverse condition; and

Fig 5 shows the overall assembly of the latching mechanism according to the second embodiment of the present invention.

Referring now to Fig 1, this shows a door 10 provided with a lock 11 having a retractable locking member 12 which is normally retracted by means of a manually engageable knob 13 or a key in the conventional manner. The latching member 12 is received in a recess in a door jamb 14 and in the normal condition is arranged to engage with a blocking member 15 which prevents the door being opened unless the latching member 12 is retracted.

In order to electrically control the lock, the blocking member 15 is pivotal in the direction of the arrow A if it is desired to permit someone without a key opening the door. The pivotal movement is sufficient to allow the latching member 12 to clear the member 15 on simply pushing the door.

Movement of the member 15 in the direction of the arrow A is controlled by a pawl 20 which engages the end of the member 15 but is capable of being moved out of the way of the end of the member 15 so as to permit the member 15 to rotate in the direction of the arrow A.

Movement of the pawl 20 is in turn electrically controlled by means of an index member 21. In one position of the index member 21 rotational movement of the pawl 20 is inhibited due to engagement with the member 21. This in turn inhibits rotational movement of the member 15 in the direction of the arrow A

when the door is pushed. However, if an electrical signal is supplied to a suitable actuator, the index member 21 is moved to a second position where, if the door is pushed, the member 15 attempts to move in the direction of the arrow A. This causes the pawl 20 to attempt to move arcuately upwards which it can now do due to the fact that the blocking member has moved to its second position. In this way, the door can simply be pushed open.

Electrical control of the member 21 is achieved by means of a piezo-electric actuator which, when pulsed, will cause the blocking member to move from the first to the second position. To ensure that mechanical forces derived from the locking member are not transferred to the piezo-electric actuator 24, the member 21 is resiliently coupled to the actuator 24 and in this case this is achieved by means of a spring 25.

A particular feature of the preferred embodiment is that the contact surfaces of the member 21 and the pawl 20 are shaped so that simply by presetting the orientation of the member 21 and pawl 20 the lock can operate so that the door can either be in a normally open or a normally closed condition and the application of the electrical control signal locks or opens the door as desired. In this embodiment this is achieved by the member 21 being provided with two projecting teeth 30 as shown in Fig 2 which are spaced apart. The contact surface of the pawl 20 is provided with mating projections and recesses with the recesses 31 being located at the same pitch as the projections 30 on the blocking member 21 and consequently spaced apart by the same amount. By arranging that on initial installation the members 21 and 20 are arranged so that the projections 30 on the member 21 are normally arranged to be received in recesses 31 in the initial unenergised condition of the piezo-electric member 24, the door will be a normally open door which when the blocking member is moved in the direction of the arrow X in Fig 2 results in the projections 30 meeting the projections 32 on the

detent 20 in the event that the door is pushed which prevents the detent from rotating and consequently the door from being opened. It will be appreciated that by initially setting the reverse conditions the door will be normally closed but will be capable of being pushed open when the blocking member is moved under the
5 control of the piezo-electric actuator so that the projections 30 mate with the recesses 31.

The manner in which the operation of the lock can be preset in either of the embodiments is a matter of design choice but could be achieved simply by providing the pivot of the pawl 20 in the form of a bar along which the detent 20 is
10 slid. Likewise, the member 21 could be moved if it were located in a slide way.

Fig 3 shows a second embodiment of the electrically activated latching mechanism according to the present invention. The same reference numerals are used as the first embodiment for the same features.

The mechanism is similar to the first embodiment and includes a strike
15 plate member 16. The strike plate 16 is positioned such that movement of the strike plate causes the movement of the member 15.

In use, a locking member (not shown) in a door pushes against the strike member 16 which causes a torque movement with rotation about axis B. This torque is transmitted to the member 15 via suitably angled surfaces to provide a
20 first stage of force reduction. The resultant torque created on the member 15 is transferred to the pawl 20 which is rotatably connected to the casing which is not shown in Fig 3. The pawl 20 and member 15 move about axis C and axis D respectively with the two axis being parallel to each other.

The index member 21, as in the first embodiment, moves radially with
25 respect to the pawl 20 and is electrically controlled by means of a piezo-electric actuator.

There are protrusions on the member 21, that correspond to protrusions on the pawl 20 such that when the two sets are aligned as in Fig 3, the index member 21 is pushed against an immovable surface that forms part of the casing, not shown. The compressive stress prevents rotation of the pawl 20 and hence the strike 16 is unable to rotate and the mechanism is locked.

Movement of the member 21 causes the protrusions to become misaligned and the pawl 20 is free to rotate and the lock is open.

Additionally, the mechanism in the second embodiment may be initially set in reverse conditions to alter the mechanism from a normally locked condition to a normally unlocked condition. This may be achieved by initially misaligning the set of protrusions 30 on the member 21 and protrusions 32 on pawl 20 as shown in Fig 4 such that the lock is open when without power and locks when power is applied.

Fig 5 shows the overall assembly of the latching mechanism. An external cam 17 is moveable to set the latching mechanism to a normally open or normally closed position by causing movement of the index member 21. The default position of the member 21 may be set by the user of the mechanism.

CLAIMS:

1. A latching mechanism arranged to receive a locking member of a lock, the mechanism comprising a means for blocking movement of the locking member in a first direction and permitting movement of the locking member in the first direction by movement in a direction transverse to the first direction and a pawl engagable with the blocking means, the pawl being electrically controllable in order to selectively control operation of the blocking means.
2. A latching mechanism according to claim 1, wherein the mechanism further comprises an electrical actuator which is in contact with an index member to electrically control the pawl, the index member and the pawl member each being provided with a plurality of protrusions.
3. A latching mechanism according to claim 1 wherein the actuator is a piezo electric actuator.
4. A latching mechanism according to claim 1 or 2, wherein movement of the actuator causes alignment between protrusions of the pawl and protrusions of the index member, to enable the latching mechanism to be in a locked condition.
5. A latching mechanism according to claim 1 or 2, wherein movement of the actuator causes misalignment of the protrusions of the pawl and the protrusions of the index member, to enable the latching mechanism to be in an unlocked condition.

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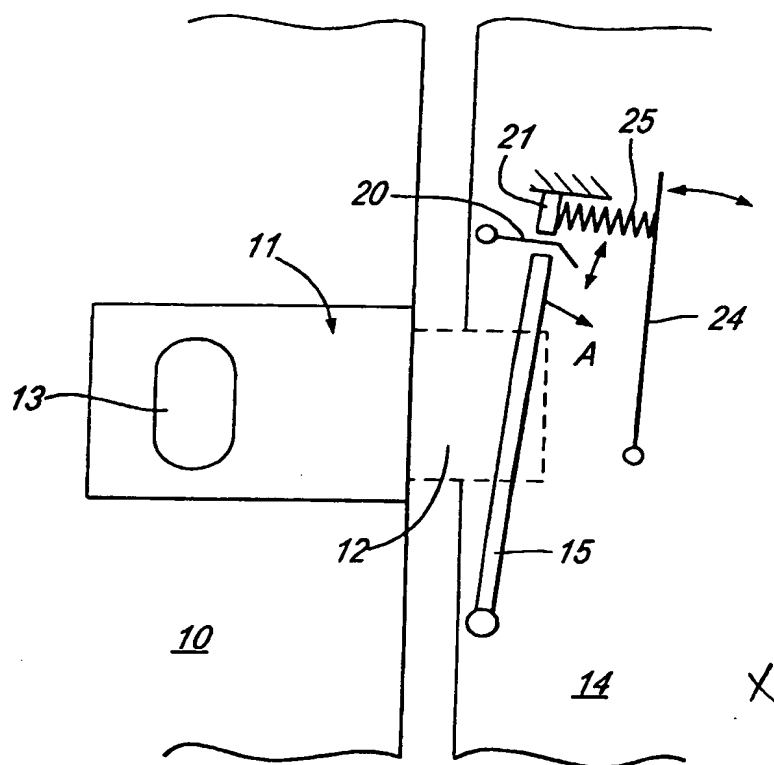


Fig. 1

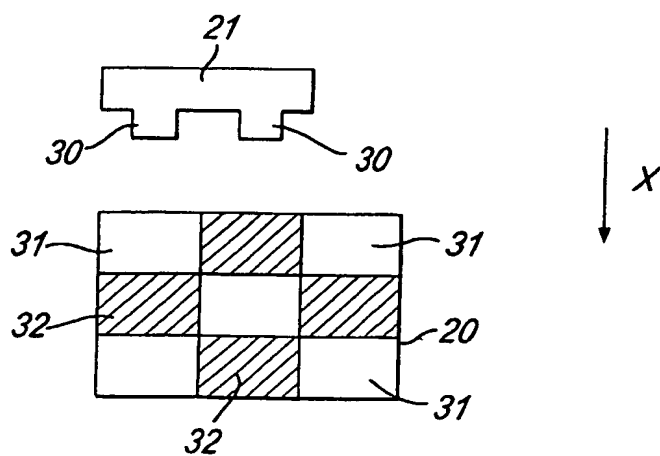
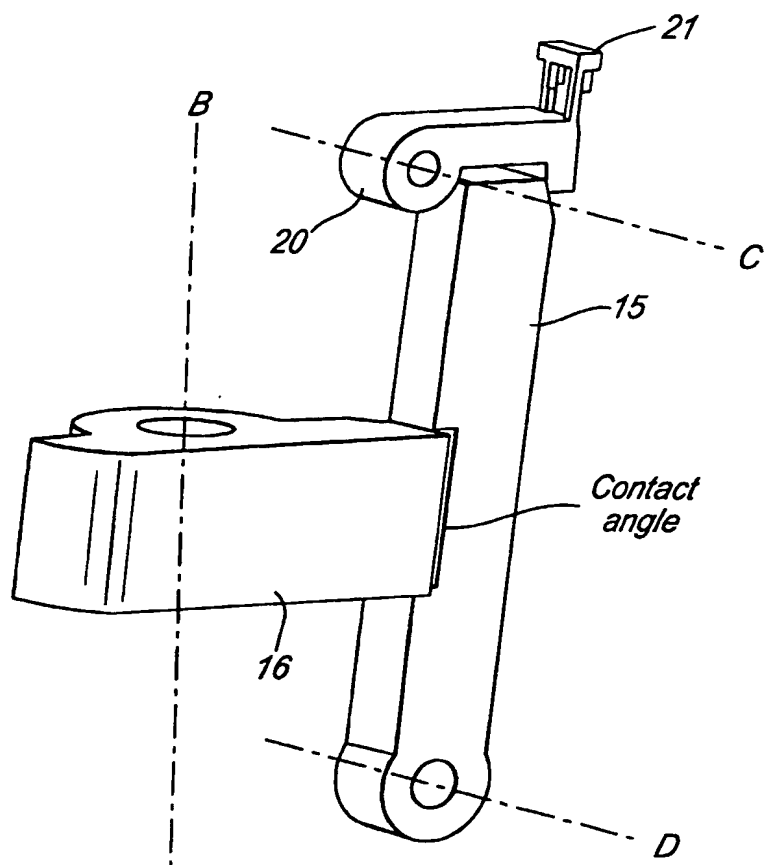
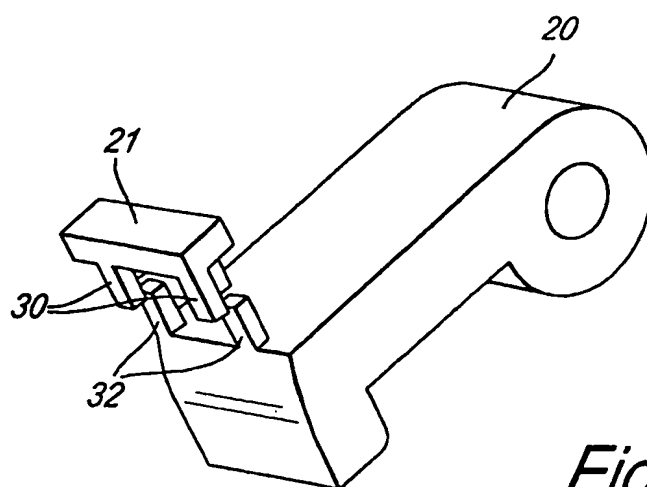
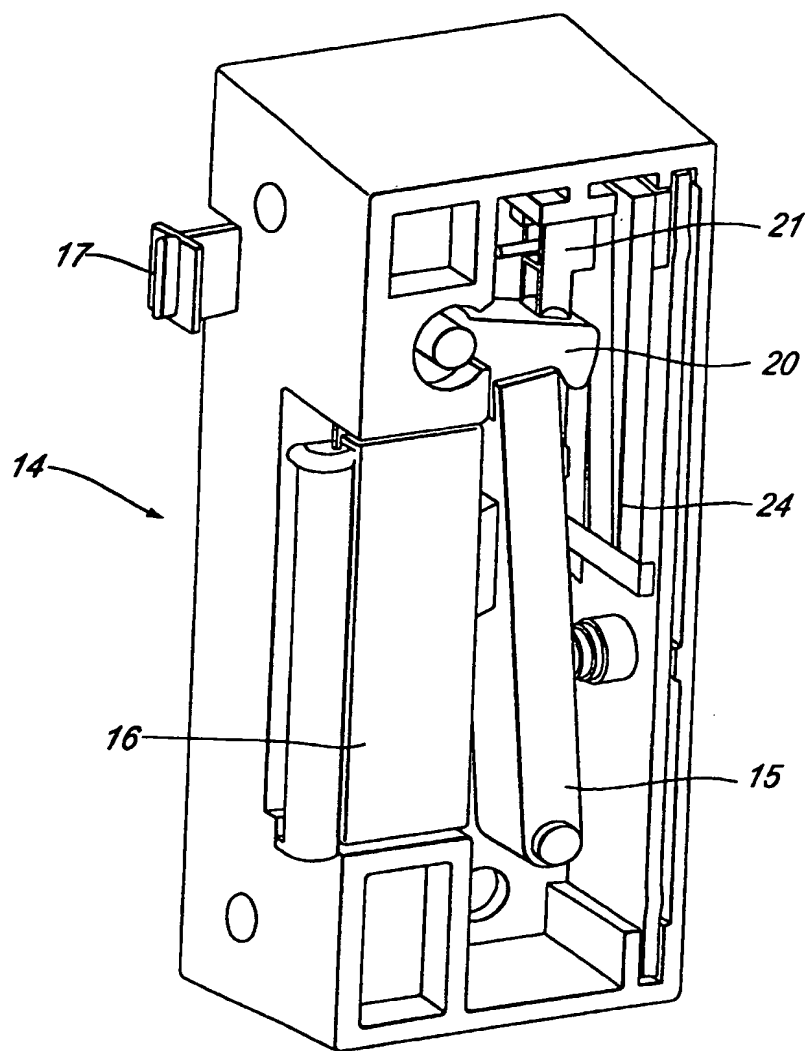


Fig. 2

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*Fig. 3**Fig. 4*

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*Fig. 5*

INTERNATIONAL SEARCH REPORT

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IPC 7 E05B47/00

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)
IPC 7 E05B

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

EPO-Internal, WPI Data, PAJ

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	DE 11 38 334 B (FUSS FRITZ KG) 18 October 1962 (1962-10-18) the whole document ----	1
X	FR 2 726 847 A (NUOVA FEB FABBRICA ELETTROAPPA) 15 May 1996 (1996-05-15) the whole document ----	1
X	EP 0 851 077 A (NUOVA F E B S R L FABBRICA ELE) 1 July 1998 (1998-07-01) the whole document ----	1
A	EP 0 757 145 A (GEZE GMBH & CO) 5 February 1997 (1997-02-05) the whole document -----	1,2

☐ Further documents are listed in the continuation of box C.☒ Patent family members are listed in annex.

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Name and mailing address of the ISA

European Patent Office, P.B. 5818 Patentlaan 2
NL - 2280 HV Rijswijk
Tel. (+31-70) 340-2040, Tx. 31 651 epo nl,
Fax: (+31-70) 340-3016

Authorized officer

Henkes, R

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Information on patent family members

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